CSE031 Digital Image Processing

Lecture 5. Color Image Processing

Color Image Processing

Color is a powerful descriptor
 Helps in object detection

Color Fundamentals



FIGURE 6.1 Color spectrum seen by passing white light through a prism. (Courtesy of the General Electric Co., Lamp Business Division.)

Color Fundamentals



FIGURE 6.2 Wavelengths comprising the visible range of the electromagnetic spectrum. (Courtesy of the General Electric Co., Lamp Business Division.)

Light and EM Spectrum

The colors that humans perceive in an object are determined by the nature of the light reflected from the object.

e.g. green objects reflect light with wavelengths primarily in the 500 to 570 nm range while absorbing most of the energy at other wavelength

Light and EM Spectrum



and black when it <u>absorbs</u> them all.



The surface of the RED is reflecting the wavelengths we see as red and absorbing all the rest.

Light and EM Spectrum

Monochromatic light: void of color Intensity is the only attribute, from black to white Monochromatic images are referred to as gray-scale images

Chromatic light bands: 0.43 to 0.79 um

The quality of a chromatic light source:

Radiance: total amount of energy

Luminance (Im): the amount of energy an observer perceives from a light source

Brightness: a subjective descriptor of light perception that is impossible to measure. It embodies the achromatic notion of intensity and one of the key factors in describing color sensation.

Color Fundamentals



FIGURE 6.3 Absorption of light by the red, green, and blue cones in the human eye as a function of wavelength.



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Color Fundamentals

The characteristics generally used to distinguish one color from another are brightness, hue, and saturation

brightness: the achromatic notion of intensity.

hue: dominant wavelength in a mixture of light waves, represents dominant color as perceived by an observer.

saturation: relative purity or the amount of white light mixed with its hue.

Color Fundamentals

Tristimulus

Red, green, and blue are denoted X, Y, and Z, respectively. A color is defined by its trichromatic coefficients, defined as

$$x = \frac{X}{X + Y + Z}$$
$$y = \frac{Y}{X + Y + Z}$$
$$z = \frac{Z}{X + Y + Z}$$

CIE Chromaticity Diagram

It shows color composition as a function of x (red) and y (green)



FIGURE 6.5 Chromaticity diagram. (Courtesy of the General Electric Co., Lamp Business Division.)

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RGB Color Model



FIGURE 6.7 Schematic of the RGB color cube. Points along the main diagonal have gray values, from black at the origin to white at point (1, 1, 1).

RGB Color Model



FIGURE 6.8 RGB 24-bit color cube.

Pixel depth

The total number of colors in a 24-bit RGB image is $(2^8)^3 =$ 16,777,216

a b

FIGURE 6.9

(a) Generating
(b) The three
(color plane
(color plane)





TABLE 6.1Valid values ofeach RGBcomponent in asafe color.

a

b FIGURE 6.10 (a) The 216 safe RGB colors. (b) All the grays in the 256-color RGB system (grays that are part of the safe color group are shown underlined).

Safe RGB colors (or safe Web colors) are reproduced faithfully, reasonably independently of viewer hardware capabilities



FIGURE 6.11 The RGB safe-color cube.

The CMY and CMYK Color Models



Equal amounts of the pigment primaries, cyan, magenta, and yellow should produce black. In practice, combining these colors for printing produces a muddy-looking black.

To produce true black, the predominant color in printing, the fourth color, black, is added, giving rise to the CMYK color model.



CMY vs. CMYK





HIS Color Model

brightness: the achromatic notion of intensity.

hue: dominant wavelength in a mixture of light waves, represents dominant color as perceived by an observer.

saturation: relative purity or the amount of white light mixed with its hue.

HIS Color Model



a b

FIGURE 6.12 Conceptual relationships between the RGB and HSI color models.



FIGURE 6.13 Hue and saturation in the HSI color model. The dot is an arbitrary color point. The angle from the red axis gives the hue, and the length of the vector is the saturation. The intensity of all colors in any of these planes is given by the position of the plane on the vertical intensity axis.

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HIS Color Model



based on (a) triangular and (b) circular color planes. The triangles and circles are perpendicular to the vertical intensity axis.

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Converting Colors from RGB to HSI

Given an image in RGB color format, the H component of each RGB pixel is obtained using the equation

$$H = \begin{cases} \theta & \text{if } B \le G \\ 360 - \theta & \text{if } B > G \end{cases}$$

$$\theta = \cos^{-1} \left\{ \frac{\frac{1}{2} \left[(R - G) + (R - B) \right]}{\left[\left(R - G \right)^2 + (R - B)(G - B) \right]^{1/2}} \right\}$$

Converting Colors from RGB to HSI

Given an image in RGB color format, the saturation component is given by

$$S = 1 - \frac{3}{(R+G+B)} \left[\min(R,G,B) \right]$$

Converting Colors from RGB to HSI

Given an image in RGB color format, the intensity component is given by

$$I = \frac{1}{3} \left(R + G + B \right)$$

Converting Colors from HSI to RGB

▶ RG sector $(0^\circ \le H < 120^\circ)$

$$B = I(1 - S)$$

$$R = I \left[1 + \frac{S \cos H}{\cos(60^\circ - H)} \right]$$
and
$$G = 3I - (R + B)$$

Converting Colors from HSI to RGB

▶ RG sector $(120^\circ \le H < 240^\circ)$

 $H = H - 120^{\circ}$ R = I(1 - S) $G = I \left[1 + \frac{S \cos H}{\cos(60^{\circ} - H)} \right]$ and

B = 3I - (R + G)

Converting Colors from HSI to RGB

▶ RG sector $(240^\circ \le H \le 360^\circ)$

 $H = H - 240^{\circ}$ G = I(1-S) $B = I \left[1 + \frac{S \cos H}{\cos(60^{\circ} - H)} \right]$ and

R = 3I - (G + B)



a b c

FIGURE 6.15 HSI components of the image in Fig. 6.8. (a) Hue, (b) saturation, and (c) intensity images.





FIGURE 6.16 (a) RGB image and the components of its corresponding HSI image: (b) hue, (c) saturation, and (d) intensity.

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FIGURE 6.17 (a)–(c) Modified HSI component images. (d) Resulting RGB image. (See Fig. 6.16 for the original HSI images.)

Basics of Full-Color Image Processing



Color Transformations

g(x, y) = T[f(x, y)]

i = 1, 2, ..., n. $S_i = T_i(r_1, r_2, ..., r_n),$





Full color



Cyan



Magenta





Black



Red





Yellow

Blue







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Intensity

g(x, y) = kf(x, y)

a b cde

FIGURE 6.31 Adjusting the intensity of an image using color transformations. (a) Original image. (b) Result of decreasing its intensity by 30% (i.e., letting k = 0.7). (c)-(e) The required RGB, CMY, and HSI transformation functions. (Original image courtesy of MedData Interactive.)



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a b c d FIGURE 6.33 Color complement transformations. (a) Original image. (b) Complement transformation functions. (c) Complement of (a) based on the RGB mapping functions. (d) An approximation of the RGB complement using HSI transformations.

Color slicing

Highlighting a specific range of colors in an image

If the colors of interest are enclosed by a cube of width W and centered at a protypical color with components $(a_1, a_2, ..., a_n)$, the necessary set of transformations is $s_i = \begin{cases} 0.5 & \text{if } \left[|r_j - a_j| > W/2 \right]_{any 1 \le j \le n} \\ r_i & \text{otherwise} \end{cases}$

Color slicing

If a sphere is used to specify the colors of interest, R_0 is the radius of the enclosing of its center. The transformations is

$$s_{i} = \begin{cases} 0.5 & \text{if } \sum_{j=1}^{n} (r_{j} - a_{j})^{2} > R_{0}^{2} \\ r_{i} & \text{otherwise} \end{cases}$$

Color slicing



a b

FIGURE 6.34 Color-slicing transformations that detect (a) reds within an RGB cube of width W = 0.2549 centered at (0.6863, 0.1608, 0.1922), and (b) reds within an RGB sphere of radius 0.1765 centered at the same point. Pixels outside the cube and sphere were replaced by color (0.5, 0.5, 0.5).



Corrected

Tone and Color Corrections



Corrected



Dark

Corrected

FIGURE 6.35 Tonal corrections for flat, light (high key), and dark (low key) color images. Adjusting the red, 43 2/15/2024 green, and blue components equally does not always alter the image hues significantly.



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FIGURE 6.36 Color balancing corrections for CMYK color images.







a b c d FIGURE 6.37 Histogram equalization (followed by saturation adjustment) in the HSI color space.

Color Image Smoothing

Let S_{xy} denote the set of coordinates defining a neighborhood centered at (x, y) in an RGB color image. The average of the RGB component vectors in this neighborhood is

$$\bar{c}(x,y) = \frac{1}{K} \sum_{(s,t)\in S_{xy}} c(s,t) = \begin{vmatrix} \frac{1}{K} \sum_{(s,t)\in S_{xy}} R(s,t) \\ \frac{1}{K} \sum_{(s,t)\in S_{xy}} G(s,t) \\ \frac{1}{K} \sum_{(s,t)\in S_{xy}} B(s,t) \end{vmatrix}$$



a b
c d
FIGURE 6.38
(a) RGB image.
(b) Red
component image.
(c) Green component. (d) Blue
component.





FIGURE 6.39 HSI components of the RGB color image in Fig. 6.38(a). (a) Hue. (b) Saturation. (c) Intensity.



a b c

FIGURE 6.40 Image smoothing with a 5×5 averaging mask. (a) Result of processing each RGB component image. (b) Result of processing the intensity component of the HSI image and converting to RGB. (c) Difference between the two results.

Color Image Sharpening

The Laplacian of vector c is

$$\nabla^2 [c(x, y)] = \begin{bmatrix} \nabla^2 R(x, y) \\ \nabla^2 G(x, y) \\ \nabla^2 B(x, y) \end{bmatrix}$$



a b c

FIGURE 6.41 Image sharpening with the Laplacian. (a) Result of processing each RGB channel. (b) Result of processing the HSI intensity component and converting to RGB. (c) Difference between the two results.

Image Segmentation Based on Color:

Segmentation in HIS Color Space

a b

c d

e



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FIGURE 6.42 Image segmentation in HSI space. (a) Original. (b) Hue. (c) Saturation. (d) Intensity. (e) Binary saturation mask (black = 0). (f) Product of (b) and (e). (g) Histogram of (f). (h) Segmentation of red components in (a).

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Segmentation in RGB Vector Space

Let the average color of interest is denoted by the RGB vector *a*. Let *z* denote an arbitrary point in RGB space.

$$D(z,a) = ||z-a|| = [(z-a)^T (z-a)]^{1/2}$$
$$= [(z_R - a_R)^2 + (z_G - a_G)^2 + (z_B - a_B)^2]^{1/2}$$



a b

FIGURE 6.44 Segmentation in RGB space. (a) Original image with colors of interest shown enclosed by a rectangle. (b) Result of segmentation in RGB vector space. Compare with Fig. 6.42(h).

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Color Edge Detection (1)

Let r, g, and b be unit vectors along the R, G, and B axis of RGB color space, and define vectors

$$\mathbf{u} = \frac{\partial R}{\partial x}\mathbf{r} + \frac{\partial G}{\partial x}\mathbf{g} + \frac{\partial B}{\partial x}\mathbf{b}$$

and

$$\mathbf{v} = \frac{\partial R}{\partial y}\mathbf{r} + \frac{\partial G}{\partial y}\mathbf{g} + \frac{\partial B}{\partial y}\mathbf{b}$$

Color Edge Detection (2)



and

$$g_{xy} = \mathbf{u} \Box \mathbf{v} = \frac{\partial R}{\partial x} \frac{\partial R}{\partial y} + \frac{\partial G}{\partial x} \frac{\partial G}{\partial y} + \frac{\partial B}{\partial x} \frac{\partial B}{\partial y}$$

Color Edge Detection (3)

The direction of maximum rate of change of c(x, y) is given by the angle

$$\theta(x, y) = \frac{1}{2} \tan^{-1} \left[\frac{2g_{xy}}{g_{xx} - g_{yy}} \right]$$

The value of the rate of change at (x, y) in the direction of $\theta(x, y)$, is given by

$$\mathbf{F}_{\theta}(x, y) = \left\{ \frac{1}{2} \left[\left(g_{xx} + g_{yy} \right) + \left(g_{xx} - g_{yy} \right) \cos 2\theta(x, y) + 2g_{xy} \sin 2\theta(x, y) \right] \right\}^{1/2}$$



a b c d FIGURE 6.46 (a) RGB image. (b) Gradient computed in RGB color vector space. (c) Gradients computed on a per-image basis and then added. (d) Difference between (b) and (c).

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a b c

FIGURE 6.47 Component gradient images of the color image in Fig. 6.46. (a) Red component, (b) green component, and (c) blue component. These three images were added and scaled to produce the image in Fig. 6.46(c).

The YIQ Model

The YIQ (luminance-inphase-quadrature) model is a recoding of RGB for colour television, and is a very important model for colour image processing. The importance of luminance was discussed a

The conversion from RGB to YIQ is given by:

Y		0.299	0.587	0.114	R
Ι	=	0.596	-0.275	-0.321	G
Q		0.212	-0.523	0.311	В

The luminance (Y) component contains all the information required for black and white television, and captures our perception of the relative brightness of particular colours. That we perceive green as much lighter than red, and red lighter than blue, is indicated by their respective weights of 0.587, 0.299 and 0.114 in the first row of the conversion matrix above. These weights should be used when converting a colour image to greyscale if you want the perception of brightness to remain the same. This is not the case for the intensity component in an HSI image.

The Y component is the same as the CIE primary Y